



Curriculum Pre/Post Test Unit 6

A. B. C.	A is a manipulator that applies a single force to the side of an object. Scoop Gripper Pinching claw Plow
А. В. С.	A is a manipulator that applies force underneath an object so it can be elevated or carried. Scoop Gripper Pinching claw Plow
А. В. С.	Another name for a friction grabber manipulator is a Scoop Claw Shovel Linkage
A. B. C.	Friction grabbers apply a force between the object and a traction pad. Vertical Normal Friction Gravitational
А. В. С.	Pinching claws require in either the object being gripped or in the claw itself to provide a solid grip. Friction Rigidity Elasticity Stiffness





6. Which type of manipulator provides quickest object pick up without requiring fine positioning of the robot? A. Scoop B. Pinching Claw C. Top jaw grabber D. Roller claw is type of robot mechanism used to pick up a large number of similar objects. A. Scoop B. Roller claw C. Accumulator D. Hopper 8. What are the two types of hoppers? A. Conveying and Lifting B. Dumping and Lifting C. Reversing and Dumping D. Lifting and Reversing 9. The objects in this type of accumulator are typically not actively manipulated once inside the storage area and are held in a fixed orientation. A. Magazine B. Hopper C. Indexing Conveyor Belt D. Non-Indexing Conveyor Belt 10. What type of accumulator runs continuously and allows the objects to self sort? A. Magazine B. Hopper C. Indexing Conveyor Belt D. Non-Indexing Conveyor Belt 11. The speed of a single belted conveyor system should be times faster than the top speed of the robot's drive train. A. 0.5 B. 1 C. 1.5

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D. 2





- 12. The speed of a double belted conveyor system should be ____ times faster than the top speed of the robot's drive train.
- A. 0.5
- B. 1
- C. 1.5
- D. 2
- 13. In which one of these type of conveyors would a ball not roll while being collected?
- A. Single belt
- B. Double belt
- C. Indexing
- D. Non-Indexing